## Carleton College, winter 2013 Math 232, Solutions to review problems and practice midterm 1 Prof. Jones

Solutions to review problems:

Chapter 1:

1. F	6. F	11. T	16. F	21. F	26. T	34. T	42. T
2. T	7. T	12. T	17. T	22. T	27. F	35. F	43. T
3. T	8. T	13. F	18. T	23. F	31. F	37. F	
4. F	9. T	14. F	19. T	24. F	32. F	39. T	
5. F	10. F	15. F	20. T	25. F	33. T	41. T	
Chapte	r 2:						
1. T	6. F	12. T	21. T	26. T	34. F	41. T	49. F
2. T	8. T	13. F	22. T	29. F	35. T	43. T	
3. F	9. T	15. F	23. T	30. T	38. T	44. F	53. T
4. T	10. F	18. T	24. F	32. T	39. F	45. T	
5. F	11. F	19. T	25. F	33. F	40. T	46. T	54. F
Chapte	r 3:						
2. F	5. T	12. T	18. T	21. T	26. T	37. F	
3. T	11. T	16 . T	20. F	22. T	29. T	41. T	

Solutions to practice exam:

1. Find all solutions of the following system of linear equations.

To find the solutions, we need to put this system into reduced row-echelon form. Adding 3 times the first equation to the second equation and 1 times the first equation to the third equation gives

Adding -1 times the second equation to the third equation and -1/3 times the second equation to the first equation and then multiplying the second equation by 1/6 gives

This is now in rref. We see that the leading variables are  $x_1$  and  $x_2$ , while the free variables are  $x_3$  and  $x_4$ . Setting  $x_3 = t_1$  and  $x_4 = t_2$ , we get that the set of solutions is

$$\left\{ \left(\frac{1}{3}t_1 - \frac{1}{3}, -\frac{1}{6}t_1 - \frac{1}{2}t_2 + \frac{1}{6}, t_1, t_2\right) \in \mathbb{R}^4 \mid t_1, t_2 \in \mathbb{R} \right\}$$

2. Let A be an  $n \times n$  matrix of rank n, and suppose that **b** is a vector in  $\mathbb{R}^n$ . Must there be  $\mathbf{v} \in \mathbb{R}^n$  with  $A\mathbf{v} = \mathbf{b}$ ? Prove or give a counter-example.

Yes. An  $n \times n$  matrix of rank n is invertible, and thus  $\mathbf{v} = A^{-1}\mathbf{b}$  is the solution we seek.

3. For each of the following subsets W of a vector space V, determine if W is a subspace of V. In each case either prove that W is a subspace or give a concrete reason why it is not a subspace.

(a) 
$$V = \mathbb{R}^4$$
, and  $W = \{(x_1, x_2, x_3, x_4) | x_1 = x_3 - x_2, \text{ and } x_4 = 0\}$ 

Observe first that  $W = \{(x_1, x_2, x_3, x_4) | x_1 + x_2 - x_3 = 0, x_4 = 0\}$ . So W is the set of vectors  $\mathbf{x} \in \mathbb{R}^4$  such that  $A\mathbf{x} = \mathbf{0}$ , with  $A = \begin{bmatrix} 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ . So W is the kernel of A, and thus is a subspace by a theorem from class.

(b) 
$$V = \mathbb{R}^4$$
, and  $W = \{(x_1, x_2, x_3, x_4) \mid x_1 = x_3 - x_2, \text{ and } x_4 = x_1 x_3\}$ 

It seems unlikely to be a subspace since the second condition  $x_4 = x_1x_3$  involves multiplication of variables and so is not linear. Indeed, we can show W is not closed under addition:  $(1, 2, 3, 3) \in W$  and  $(-1, 2, 1, -1) \in W$  but their sum (0, 4, 4, 2) is not in W since it fails the condition  $x_4 = x_1x_3$ . You could also proceed by showing that W is not closed under scalar multiplication:  $(1, 2, 3, 3) \in W$ , but 2(1, 2, 3, 3) = (2, 4, 6, 6) is not in W.

4. (a) Let  $A = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$ . Show that  $A^2 = 0$  and that  $A + I_2$  is invertible.

This is a direct computation, first of  $A^2$ , and then of the determinant of  $A + I_2$ , which is 1. Since  $A + I_2$  has non-zero determinant, it is invertible.

(b) Suppose that A is an  $n \times n$  matrix with  $A^2 = 0$ . Must  $A + I_n$  always be invertible? Either explain why or give a counter-example.

Yes. We have  $(A + I_n)(A - I_n) = A^2 + I_n A - AI_n + I_n I_n = 0 + A - A + I_n = I_n$ , where we have used several properties of  $I_n$ . Thus there is a matrix B such that  $(A + I_n)B = I_n$  (we can take  $B = A - I_n$ ). So by a theorem from class,  $A + I_n$  is invertible.

- 5. Find all the vectors in the kernel of each of the following linear transformations, and justify your answers.
  - (a) The shear  $T(\mathbf{x}) = \begin{bmatrix} 1 & -5 \\ 0 & 1 \end{bmatrix} \mathbf{x}.$

The matrix has non-zero determinant, and so is invertible. Thus the only  $\mathbf{x}$  with  $T(\mathbf{x}) = \mathbf{0}$  is  $\mathbf{x} = A^{-1}\mathbf{0} = \mathbf{0}$ . So the kernel of T is  $\{\mathbf{0}\}$ .

- (b) Reflection about a plane in ℝ<sup>3</sup>.
  This transformation is again invertible (it is its own inverse, since T(T(**x**)) = **x** for all **x**), so it has kernel {**0**}.
- (c)  $T : \mathbb{R}^2 \to \mathbb{R}^2$  given by projection onto the line y = x. The kernel consists of the vectors that project to **0**, which are precisely those that lie along the line perpendicular to y = x. That line is y = -x, also known as the span of the vector  $\begin{bmatrix} 1\\ -1 \end{bmatrix}$ .
- (d)  $T(\mathbf{x}) = A\mathbf{x}$ , where A is an  $n \times m$  matrix of rank m. We seek all solutions to  $A\mathbf{x} = \mathbf{0}$ . So we put the augmented matrix  $[A|\mathbf{0}]$  into rref, and we find there is a leading 1 in each column (since the rank of the matrix equals the number of columns). Thus there are no free variables, and it follows that  $A\mathbf{x} = \mathbf{0}$  has a unique solution. Hence the kernel of T consists only of  $\mathbf{0}$ .
- 6. Given subspaces  $W_1$  and  $W_2$  of  $\mathbb{R}^n$ , set

$$W_1 + W_2 = \{ \mathbf{x} \in V : \mathbf{x} = \mathbf{w_1} + \mathbf{w_2} \text{ for some } \mathbf{w_1} \in W_1 \text{ and } \mathbf{w_2} \in W_2 \}.$$

Prove that  $W_1 + W_2$  is a subspace of V.

Let **x** and **y** be in  $W_1 + W_2$ , meaning that  $\mathbf{x} = \mathbf{x_1} + \mathbf{x_2}$  for some  $\mathbf{x_1} \in W_1$ ,  $\mathbf{x_2} \in W_2$  and  $\mathbf{y} = \mathbf{y_1} + \mathbf{y_2}$  for some  $\mathbf{y_1} \in W_1$ ,  $\mathbf{y_2} \in W_2$ . Then

$$x + y = x_1 + x_2 + y_1 + y_2 = (x_1 + y_1) + (x_2 + y_2)$$

Since  $W_1$  is a subspace,  $\mathbf{x_1} + \mathbf{y_1} \in W_1$ , and since  $W_2$  is a subspace,  $\mathbf{x_2} + \mathbf{y_2} \in W_2$ . We've thus written  $\mathbf{x} + \mathbf{y}$  as an element of  $W_1$  plus an element of  $W_2$ , showing that  $\mathbf{x} + \mathbf{y} \in W_1 + W_2$ .

Now let  $\mathbf{x} \in W$  and c be a scalar, so that  $\mathbf{x} = \mathbf{x_1} + \mathbf{x_2}$  for some  $\mathbf{x_1} \in W_1$ ,  $\mathbf{x_2} \in W_2$ . Then  $c\mathbf{x} = c(\mathbf{x_1} + \mathbf{x_2}) = c\mathbf{x_1} + c\mathbf{x_2}$ , and this last expression is the sum of an element of  $W_1$  and an element of  $W_2$ , and so is in  $W_1 + W_2$ .

- 7. Let  $V = \mathbb{R}^2$  and  $S = \left\{ \begin{bmatrix} 2\\2 \end{bmatrix}, \begin{bmatrix} 2\\-2 \end{bmatrix} \right\}.$ 
  - (a) Show that  $\begin{bmatrix} 1\\2 \end{bmatrix}$  is in Span(S). [Hint: this is the same as solving a certain system of equations]

We need to find weights  $x_1$  and  $x_2$  such that  $x_1 \begin{bmatrix} 2\\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 2\\ -2 \end{bmatrix} = \begin{bmatrix} 1\\ 2 \end{bmatrix}$ . Equating coordinates gives

Adding -1 times the first equation to the second gives

We now divide the first equation by 2 and multiply the second equation by -1/4. Finally, we add -1 times the new second equation to the first equation, and this gives the echelon form

$$x_1 = \frac{3}{4}$$
$$x_2 = -\frac{1}{4}$$
We have thus shown that  $\begin{bmatrix} 1\\2 \end{bmatrix} = \frac{3}{4} \begin{bmatrix} 2\\2 \end{bmatrix} - \frac{1}{4} \begin{bmatrix} 2\\-2 \end{bmatrix}$ , proving that  $\begin{bmatrix} 1\\2 \end{bmatrix}$  is in Span(S).

(b) Show that every vector  $(b_1, b_2)$  in  $\mathbb{R}^2$  is in Span(S).

The calculation is very similar to that of part (a). Let  $\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \in \mathbb{R}^2$ , and look for weights  $x_1, x_2$  satisfying  $x_1 \begin{bmatrix} 2 \\ 2 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ -2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ . Equating coordinates gives

Adding -1 times the first equation to the second gives

$$\begin{array}{rcrcrcrc} 2x_1 & +2x_2 & = & b_1 \\ & -4x_2 & = & b_2 - b_1 \end{array}$$

We now divide the first equation by 2 and multiply the second equation by -1/4. Finally, we add -1 times the new second equation to the first equation, and this gives the echelon form

$$\begin{array}{rcl} x_1 & = & (1/2)b_1 + 1/4(b_2 - b_1) \\ x_2 & = & -1/4(b_2 - b_1) \end{array}$$

Thus the system of equations has a solution, proving that  $\begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$  is in Span(S). Thus Span(S) =  $\mathbb{R}^2$ .

8. Let S be a non-empty subset of  $\mathbb{R}^n$ . Assume that each vector in Span(S) can be written in one and only one way as a linear combination of vectors in S. Show that S is linearly independent. Suppose that we have  $a_1\mathbf{x_1} + \cdots + a_n\mathbf{x_n} = \mathbf{0}$  with  $\mathbf{x_i} \in S$ . We know that  $\mathbf{0}$  can also be written as the linear combination

$$0\mathbf{x_1} + \cdots + 0\mathbf{x_n}.$$

Since  $\mathbf{0} \in \text{Span}(S)$ , our hypothesis gives us that there is only one way to write  $\mathbf{0}$  as a linear combination of vectors in S. Therefore we must have  $a_1 = 0, \ldots, a_n = 0$ . Hence S is linearly independent.